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A

PATENT APPLICATION TRANSMITTAL LETTER
(Small Entity)

Docket No.
HAMAR-119

TO THE ASSISTANT COMMISSIONER FOR PATENTS

Transmitted herewith for filing under 35 U.S.C. 111 and 37 C.F.R. 1.53 is the patent application of:

Martin R. Hamar

For: **LASER TARGET ASSEMBLY FOR SHEAVES AND HEIGHT GAGES**

Enclosed are:

- ☒ Certificate of Mailing with Express Mail Mailing Label No. **EL681778386US**
- ☒ **four (4)** sheets of drawings.
- ☐ A certified copy of a _____ application.
- ☒ Declaration ☒ Signed. ☐ Unsigned.
- ☒ Power of Attorney
- ☒ Information Disclosure Statement
- ☐ Preliminary Amendment
- ☒ Verified Statement(s) to Establish Small Entity Status Under 37 C.F.R. 1.9 and 1.27.
- ☐ Other: _____

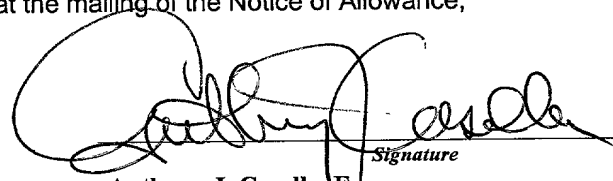
jc675 U.S. PTO
09/684029
10/06/00

CLAIMS AS FILED

For	#Filed	#Allowed	#Extra	Rate	Fee
Total Claims	22	- 20 =	2	x \$9.00	\$18.00
Indep. Claims	3	- 3 =	0	x \$40.00	\$0.00
Multiple Dependent Claims (check if applicable) <input type="checkbox"/>					\$0.00
BASIC FEE					\$355.00
TOTAL FILING FEE					\$373.00

- ☒ A check in the amount of **\$373.00** to cover the filing fee is enclosed.
- ☐ The Commissioner is hereby authorized to charge and credit Deposit Account No. _____ as described below. A duplicate copy of this sheet is enclosed.
 - ☐ Charge the amount of _____ as filing fee.
 - ☒ Credit any overpayment.
 - ☒ Charge any additional filing fees required under 37 C.F.R. 1.16 and 1.17.
 - ☐ Charge the issue fee set in 37 C.F.R. 1.18 at the mailing of the Notice of Allowance, pursuant to 37 C.F.R. 1.311(b).

Dated: **October 6, 2000**


Signature

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IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

Applicant: Martin R. Hamar

Appl. No.: --

Filed: Concurrently herewith

For: LASER TARGET ASSEMBLY FOR SHEAVES AND HEIGHT GAGES

Box PATENT APPLICATION
Assistant Commissioner for Patents
Washington, D.C. 20231

**DECLARATION BY SMALL BUSINESS
CONCERN CLAIMING SMALL ENTITY STATUS**

Sir:

I hereby declare that I am an Officer of Hamar Laser Instruments, Inc.

I hereby declare that Hamar Laser Instruments, Inc. qualifies as a small business concern as defined in 13 CFR 121.3-18, and reproduced in 37 CFR 1.9(d), for purposes of paying reduced fees under section 41(a) and (b) of Title 35, United States Code, in that the number of employees of the concern, including those of its affiliates, DOES NOT EXCEED 500 PERSONS. For purposes of this statement, (1) the number of employees of the business concern is the average over the previous fiscal year of the concern of the persons employed on a full-time, part-time or temporary basis during each of the pay periods of the fiscal year, and (2) concerns are affiliates of each other when either, directly or indirectly, one concern controls or has the power to control the other, or a third party or parties controls or has the power to control both.

I hereby declare that rights under contract or law have been conveyed to and remain with the small business concern identified above with regard to the invention, entitled "LASER TARGET ASSEMBLY FOR SHEAVES AND HEIGHT GAGES" invented by Martin R. Hamar described in the application filed concurrently herewith.

I hereby declare that the rights held by the above-identified small business concern are exclusive, and no rights to the invention are held by any person, other than the inventor, who could not qualify as an independent inventor under 37 CFR 1.9(c) or by any concern which would not qualify as a small business concern under 37 CFR 1.9(d) or a nonprofit organization under 37 CFR 1.9(e).

I acknowledge the duty to file, in this application or patent, notification of any change in status resulting in loss of entitlement to small entity status prior to paying, or at the time of paying, the earliest of the issue fee or any maintenance fee due after the date on which status as a small entity is no longer appropriate (37 CFR 1.28(b)).

I hereby declare that all statements made herein of my own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under Section 1001 of Title 18 of the United States code, and that such willful false statements may jeopardize the validity of the application, any patent issuing thereon, or any patent to which this declaration is directed.

HAMAR LASER INSTRUMENTS, INC.

By: 

Name : Martin R. Hamar

Title : President

Dated: July 24, 2000

INVENTOR: MARTIN R. HAMAR

ASSIGNEE: HAMAR LASER INSTRUMENTS, INC.

ATTY. REF.: HAMAR-119

LASER TARGET ASSEMBLY FOR SHEAVES AND HEIGHT GAGES

LASER TARGET ASSEMBLY FOR SHEAVES AND HEIGHT GAGES

This application claims the benefit of the filing date of Provisional Patent Application, U.S. Serial No. 60/188,413 filed March 10, 2000, the disclosure of which is incorporated herein by reference.

BACKGROUND OF THE INVENTION

1. Field of the Invention. The subject invention relates to a target assembly for use with a laser apparatus and a control or readout apparatus for assessing the alignment of a sheave or for properly aligning a height gage.

2. Description of the Related Art. Many prior art machines include parts that are movable relative to one another. Optimum efficiency of the machines can be achieved when the movable parts are properly aligned relative to one another. However, use of the prior art machines invariably results in the respective movable parts becoming misaligned relative to one another.

The prior art also includes assemblies with parts that must be positioned at a specified location relative to a fixed frame of reference.

The prior art includes many types of apparatus for assessing the alignment of two parts relative to one another. These prior art alignment devices include mechanical devices, such as levels, optical devices, such as sight gages, and electrical devices.

The assignee of the subject invention has developed several alignment systems that employ at least one laser emitter, at least one light-sensitive target cell, a control system and/or readout device. The prior art laser emitter projects a substantially straight laser beam toward the light-sensitive target cell. The prior art target cell identifies the location of the center of energy of the laser beam that impinges on the target cell. The

target cell generates signals that can be analyzed by the control system to assess the relative position of the target relative to the laser and to assess the alignment of the laser beam impinging on the target. The data developed in this manner can be used to adjust the position and/or alignment of one or the other of the components being aligned.

The prior art systems of laser emitters and targets have been used very successfully to align parts relative to a specified central axis. For example, a prior art laser alignment system has been used to align rotors and stators along the rotational axis of a turbine. Another prior art laser alignment system has been used to align a rotating tool, such as a drill, to a work piece upon which the tool will act. An example of a prior art laser alignment system for projecting a rotational axis is shown in the assignee's U.S. Patent No. 4,566,202.

The assignee of the subject invention also has developed an apparatus for sweeping at least one laser plane. This prior art apparatus works by directing a laser beam into a penta-prism that reflects an input laser beam internally and produces an output beam that is aligned precisely at right angles to the input beam. The penta-prism then is rotated about the axis of the input beam. As a result, the output beam sweeps an laser plane that is perpendicular to the input beam. Targets can be mounted on objects at locations remote from the laser emitter. The positions of these targets and the objects to which the targets are mounted then can be determined precisely by signals generated as the laser beam sweeps across the targets. An apparatus that sweeps such a flat laser plane is disclosed in the assignee's earlier U.S. Patent No. 4,468,119. An apparatus capable of sweeping a plurality of mutually perpendicular planes is disclosed in the assignee's U.S. Patent No. 5,307,368. The assignee's U.S. Patent No. 5,929,984

discloses a system for generating at least one laser scan plane and laser beams that are perpendicular to the plane. The system disclosed in the assignee's U.S. Patent No. 5,929,984 can be used, for example, to properly position components of an airplane during the manufacture of the airplane.

A sheave is an apparatus that has at least two grooved disks or wheels that rotate about parallel axes. Sheaves also are referred to as pulleys. Sheave systems are incorporated into many industrial machines where the grooved disks or wheels are mounted to parallel shafts and where belts, timing chains or gears are used to rotate parts of the machine about parallel axes. The efficiency of the machine depends partly upon the alignment of the various rotating members. Use of a machine causes bearings to wear and can misalign other supports for the rotating parts. Such misalignment can lead to an accelerated wear and can cause a premature breakage of parts of the machine. Misalignment of rotating components of a sheave system also can degrade the quality of the products being produced by the machine. Additionally, breakage of machine parts leads to downtime of the machine and can impose a very substantial cost penalty on the manufacturing process. Accordingly, there is a demand for an apparatus to accurately assess sheave alignment. The above-described prior art laser apparatus is well suited to checking the alignment of components along a single rotational axis or for checking the position and alignment of parts relative to a reference plane. However, use of the prior art laser apparatus to check parallelism between a plurality of spaced apart rotational axes has been somewhat complicated. Typically, the job of checking machine alignment is assigned to the mechanic or technician who operates the machine. The typical technician may not have the time to perform a complicated sheave alignment check using the prior art

laser apparatus. Instead, the technician may employ common “eyeball” methods of sheave alignment using a straight-edge. However, these “eyeball” methods don’t provide the necessary accuracy because these methods use the faces of the sheaves, which are rarely parallel to the grooves of the sheaves, as a reference.

Some prior art alignment procedures employ a height gage to check the height of one member relative to another. The prior art apparatus for checking the height of one member relative to another have included line levels and optical sight gages. The prior art laser apparatus also is well suited for this purpose. In particular, the prior art laser apparatus can be used to direct a beam from a first member or reference point to a second member. A target may be positioned on the second member, and the height of one member relative to the other can be determined by readings taken on the target. A target of this type often may be mounted on a target pole that enables the target to be moved vertically along the pole. The position of the target on the pole can be accurately determined mechanically or electromechanically. More accurate height information then can be achieved with the photosensitive target. This combination of a laser emitter, a photosensitive target and a target pole will yield very precise readings when the target pole is aligned perfectly vertically. However, the precision enabled by the combination of the laser emitter and photosensitive target can be offset if the target pole is not perfectly vertical. Accordingly, there is a demand for a laser alignment system with a height gage that compensates for misalignment of the target pole from a true vertical alignment.

SUMMARY OF THE INVENTION

The subject invention relates to a target assembly for use with a laser, and particularly a laser capable of sweeping a flat optical plane. The target assembly comprises three light-sensitive target cells arranged in a triangle. The target cells may be mounted to a support and face substantially in a common direction relative to the support. The cell planes of two target cells may be coplanar, and the cell planes of all three target planes may be parallel. Preferably, the three targets are arranged to define a substantially equilateral triangle.

The support may include mounting means for mounting the target assembly to a sheave. Alternatively, the support may include mounting means for mounting the target assembly to a height gage. When used for sheave alignment, the support may include mounting structure for mounting the target assembly substantially vertically to a sheave or pulley wheel. When used with a height gage, the support can be mounted substantially horizontally and perpendicular to the target pole. In either embodiment, the mounting means of the support is formed for face-to-face engagement with the grooves of a sheave to allow genuine groove-to-groove alignment. The light-sensitive target cells may be two axis targets capable of generating X and Y coordinates for a laser beam impinging thereon. The target cells may be analog or digital, and in certain embodiments the light-sensitive target cells may be a CCD (charged coupling device).

The target assembly is used by first mounting the laser apparatus on a reference structure to which alignment of an adjustable member will be compared. For example, the reference may be one rotational sheave member in a sheave apparatus.

The laser apparatus is leveled and trued by leveling mechanisms incorporated into the apparatus.

The target assembly then is mounted to a portion of the apparatus that is to be aligned. More particularly, the target assembly is mounted such that the support plate of the target assembly is approximately parallel to the optical plane that will be swept by the laser apparatus. Additionally, the target assembly is mounted such that all three light-sensitive target cells substantially face the laser, with one light-sensitive target cell being relatively close to the laser and with the two remaining light-sensitive target cells being spaced further from the laser.

The laser apparatus then is operated to sweep a flat optical plane, such that the laser impinges upon the respective target cells. Readings then are taken by the target cells to identify locations that are impinged upon by the laser. A difference in readings between the two target cells furthest from the laser apparatus will identify a pitch error between the plane of the three target cells and the laser scan plane. Similarly, a difference between the target cell closest to the laser and the average reading on the two more distant target cells (groove) will provide a yaw error reading.

In the typical sheave alignment operation, the support to which the light-sensitive target cells are mounted will be aligned substantially vertical on the sheave. However, the apparatus can be used with a height gage. When the target assembly is used with a height gage, the planar support to which the light-sensitive target cells are mounted will be substantially horizontal and at a selected elevational position on a target pole. Differences in readings of the respective targets can be used to precisely measure

roll and pitch, and thereby to enable mathematical compensation for an alignment of the target pole other than perfectly vertical.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1A is a perspective view of a laser and target assembly mounted to a sheave system.

FIG. 1B is a perspective view of a mounting plate in accordance with the subject invention.

FIG. 1C is a top plan view of a mounting plate of the subject invention engaging the grooves of a sheave.

FIG. 2 is a perspective view of a target assembly in accordance with the subject invention and adapted for use with a sheave laser alignment system.

FIG. 3 is a perspective view of a target assembly adapted for use with a height gage.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

A laser alignment system in accordance with a first embodiment of the invention is identified by the numeral 10 in FIG. 1. The laser alignment system 10 is specifically intended for aligning components of a prior art sheave system 12. The sheave system 12 includes a first sheave 14 mounted to a first rotational axis 16 and having circumferential grooves 18. The sheave system also includes a second sheave 20 mounted to a second rotational axis 22 and having circumferential grooves 24. Belts 26 are mounted in the grooves 18 and 24 and deliver rotation forces from one sheave to another. Ideally the axes 16 and 22 are parallel. However perfect parallelism may not exist. The laser alignment system 10 enables a check of the relative positions and alignment of the sheaves 14 and 20 so that adjustments can be made.

The laser alignment system 10 includes a laser module 28 and a target module 30. The laser module 28 is operative to sweep a plane, as shown schematically in FIG. 1.

Referring to FIG. 1A-C, the target module 30 comprises a mounting plate 32, a support plate 34 and three light-sensitive target cells A, B and C. The mounting plate 32 includes fixtures for mounting the target module 30 to a groove 24 in the sheave 20. The particular mounting structures on the mounting plate 32 may vary depending upon specifics of a sheave system 12 to be aligned. Typically, the mounting plate 32 is a three-ball mount which qualifies the module 30 in the sheave grooves 24. The balls 36, 38 are arranged in an L-shaped pattern with two balls 38 residing in one groove and one ball 36 residing in a different groove. The single ball 36 is adjustable axially along slot 39 so that it can sit properly in its own groove. It can be appreciated that there can be a single

ball per groove to increase the stability of the target module 30. An exactly similar arrangement is used to mount the laser module 28 in its sheave.

The support plate 34 is rigidly and permanently mounted to the mounting plate 32. The target cells A, B and C are permanently mounted to the support plate 34 at the target module manufacturing location. The mounting of the photosensitive target cells A, B and C is such that the respective target cells A, B and C all face substantially in the same direction. Additionally, photosensitive target cells B and C are substantially coplanar and target cell A is substantially parallel to the coplanar cell planes of the light-sensitive target cells B and C. Furthermore, all three light-sensitive target cells A, B and C have their vertical axes disposed in a common plane that lies substantially parallel to the plane of the support plate 34.

The target assembly is used with the laser module 28 shown schematically in FIG. 1. The laser module 28 is operative to sweep a laser plane, and specifically the laser module 28 may be any of the known laser devices manufactured by Hamar Laser Instruments, Inc. and capable of sweeping a laser plane. The laser module 28 is mounted to a groove 18 on the first sheave 14, and the optical plane generated by the laser module 28 will define a reference plane to which the adjustable rotational axis 22 and the sheave 20 will be compared. The scan angle of the laser module 28 used to create the reference plane is preferably 26 degrees. The laser module 28 is leveled to ensure that the optical plane is substantially perfectly vertical.

The apparatus 10 may further include a computer connected to the light-sensitive target cells A, B and C for receiving signals produced by the target cells A, B and C and for performing basic mathematical operations that convert the signals received from

the target cells A, B and C to alignment data or required correction data. The control system embodied in the computer may be of the type disclosed in U.S. Patent No. 4,679,940 and/or of the type incorporated into other alignment systems marketed by Hamar Laser Instruments, Inc.

As shown schematically in FIG. 2, the target module 30 can calculate pitch errors by comparing the readings of the light-sensitive target cells B and C. In particular, a pitch misalignment will be proportional to the differences between readings of the light-sensitive target cells B & C, as represented by the formula $PITCH = B - C$.

A displacement error of the groove 24 relative to the groove 18 can be calculated as one-half the sum or average of the B and C readings, as represented by the formula $GROOVE = (B + C)/2$. A yaw error can be calculated using the difference between the A target cell reading and the average groove displacement reading, as represented by the formula $YAW = A - GROOVE$. For clarity, FIG. 2 shows the relative alignment of errors identified as pitch, groove and yaw.

FIG. 3 shows exactly the same concept as FIGS. 1 and 2, but applied to a height gage system. In particular, the target module of FIG. 3 is identified generally by the numeral 40 and includes a target pole 42 having a measuring tip 44 at one end thereof. A support plate 46 is mounted to the target pole 42 at a location remote from the measuring tip 44. The support plate 46 is substantially perpendicular to the target pole 42.

The target module 40 further includes three light-sensitive target cells A, B and C respectively. The light-sensitive target cells A, B and C are precisely mounted under controlled factory conditions to face substantially from the same direction at known distances and spacings from one another. Additionally, the light-sensitive target cells A, B

and C are mounted such that their horizontal reference lines define a common plane that is substantially parallel to the plane defined by the support plate 46.

The target module 40 is used substantially in the same manner as the target module 28 described and illustrated above. In particular, the target module 40 is used with a laser apparatus capable of sweeping a flat optical plane. The laser apparatus is mounted to a fixed reference point and is leveled. The measuring tip 44 of the target pole 42 then is placed on the object that requires a positioning or height check. The laser module then is operated to sweep a horizontal scan plane that impinges upon the respective light-sensitive target cells A, B and C. Differences between readings on the target cells B and C will identify a roll error ($ROLL = B - C$). A pitch error can be calculated as the difference between a reading on the A target and the average of the readings on the B and C targets ($PITCH = A - (B + C)/2$). Elevation is the average of all three target readings $(A + B + C)/3$.

A significant advantage of the three-target module 40 is that the angular position of the target pole 42 of the height gage target module 40 relative to the laser plane is readily determined by the differences in the three cells as described above in the description of the sheave target system. Thus, an accurate reading with the height gage module 40 does not require the technician to initially square the target pole 42. Rather, this squaring or truing of the target pole 42 can be carried out mathematically.

While the invention has been described with respect to a preferred embodiment, it is apparent that various changes can be made without departing from the scope of the invention as defined by the appended claims.

WHAT IS CLAIMED IS:

1. A target assembly for a laser alignment system, the target assembly comprising three light-sensitive target cells fixedly mounted in proximity to one another to define corners of a triangle, the light-sensitive target cells all facing in a common direction.
2. The target assembly of claim 1, further comprising a support plate, the three light-sensitive target cells being mounted to the support plate.
3. The target assembly of claim 2, wherein each said target cell has first and second perpendicular axes, the first axes of said target cells being mutually parallel to one another, the second axes of the target cells being coplanar and substantially parallel to the support plate.
4. The target assembly of claim 3, further comprising means for mounting the target assembly to a sheave such that the support plate and the second axes of the respective light-sensitive target cells are aligned substantially perpendicular to a rotational axis of the sheave.
5. The target assembly of claim 4, wherein said means for mounting the target assembly is a ball mount, said ball mount includes at least one ball to engage a groove of said sheave.
6. The target assembly of claim 4, wherein said means for mounting the target assembly is a ball mount, said ball mount includes a plurality of balls arranged in an L-shaped pattern to engage a plurality of grooves of said sheave.
7. The target assembly of claim 6, wherein at least one said ball of the plurality of balls is adjustable to properly engage said grooves of said sheave.

8. A target assembly as in claim 3, further comprising a target pole, said support plate being mounted to an end of the target pole such that the support plate and the second axes of the respective light-sensitive target cells are substantially perpendicular to the target pole.

9. A sheave laser alignment system, said system aligns a rotational axis of a first sheave to a parallel rotational axis of a second sheave, said system comprising:

a laser module operative to sweep a reference plane, said laser module mounted to a groove on said first sheave; and

a target assembly mounted to a groove on said second sheave.

10. The system of claim 9, wherein the target assembly comprises three light-sensitive target cells fixedly mounted in proximity to one another to define corners of a triangle, the light-sensitive target cells all facing in a common direction.

11. The system of claim 10, wherein the target assembly further comprises a support plate, the three light-sensitive target cells being mounted to the support plate.

12. The system of claim 11, wherein each said target cell has first and second perpendicular axes, the first axes of said target cells being mutually parallel to one another, the second axes of the target cells being coplanar and substantially parallel to the support plate.

13. The system of claim 12, further comprising means for mounting the target assembly to said sheave such that the support plate and the second axes of the respective light-sensitive target cells are aligned substantially perpendicular to said rotational axis of the sheave.

14. The system of claim 13, wherein said means for mounting the target assembly is a ball mount, said ball mount includes at least one ball to engage a groove of said sheave.

15. The system of claim 13, wherein said means for mounting the target assembly is a ball mount, said ball mount includes a plurality of balls arranged in an L-shaped pattern to engage a plurality of grooves of said sheave.

16. The system of claim 15, wherein at least one said ball of the plurality balls is adjustable to properly engage said grooves of said sheave.

17. The system of claim 12, further comprising a target pole, said support plate being mounted to an end of the target pole such that the support plate and the second axes of the respective light-sensitive target cells are substantially perpendicular to the target pole.

18. A method of aligning components of a sheave system, said sheave system includes a first sheave having circumferential grooves, said first sheave mounted to a first rotational axis and a second sheave having circumferential grooves, said second sheave mounted to a second rotational axis, said method comprising:

fixing a laser module to the grooves of said first sheave;

fixing a target assembly to the grooves of said second sheave;

generating a reference plane by said laser module;

measuring alignment data received from said target assembly;

calculating correction data based on the measured alignment data; and

adjusting said first and second sheave until said correction data is within an acceptable range.

19. A method as in claim 18, wherein the step of fixing a target assembly to the grooves of said second sheave includes providing three light-sensitive target cells fixedly mounted in said target assembly, said cells mounted in proximity to one another to define corners of a triangle, the cells all facing in a common direction, said target assembly arranged such that two said cells lie in the same perpendicular plane to the generating direction of the reference plane and are positioned further away from said laser module than a first cell.

20. A method as in claim 19, wherein the step of calculating correction data includes calculating a pitch error by comparing the measuring alignment data of the two furthest said cells of said target assembly.

21. A method as in claim 20, wherein the step of calculating correction data includes calculating a displacement error of the grooves by averaging the measuring alignment data of the two furthest said cells of said target assembly.

22. A method as is claim 21, wherein the step of calculating the correction data includes calculating a yaw error by finding the difference between the measuring alignment data of said first cell closest to said laser module and said displacement error of the grooves.

ABSTRACT OF THE DISCLOSURE

A target assembly is provided for use with a laser alignment system. The target assembly includes three light-sensitive target cells arranged to define corners of a triangle. The light-sensitive target cells are mounted to a support plate such that the three light-sensitive target cells face substantially in the same direction, and such that one axis of each light-sensitive target cell is substantially parallel to the plane of the support plate. The support plate may further include mounting structures for mounting the target assembly to an object that must be checked or aligned. Differences between readings can be used to check misalignment about two perpendicular axes, and averages of the respective readings can be used to check position or displacement. The laser alignment system can be employed to align the parallel rotational axes of a driven and driving sheave of an industrial machine. By mounting the target assembly to the grooves of a sheave, the alignment system can achieve true groove-to-groove alignment.

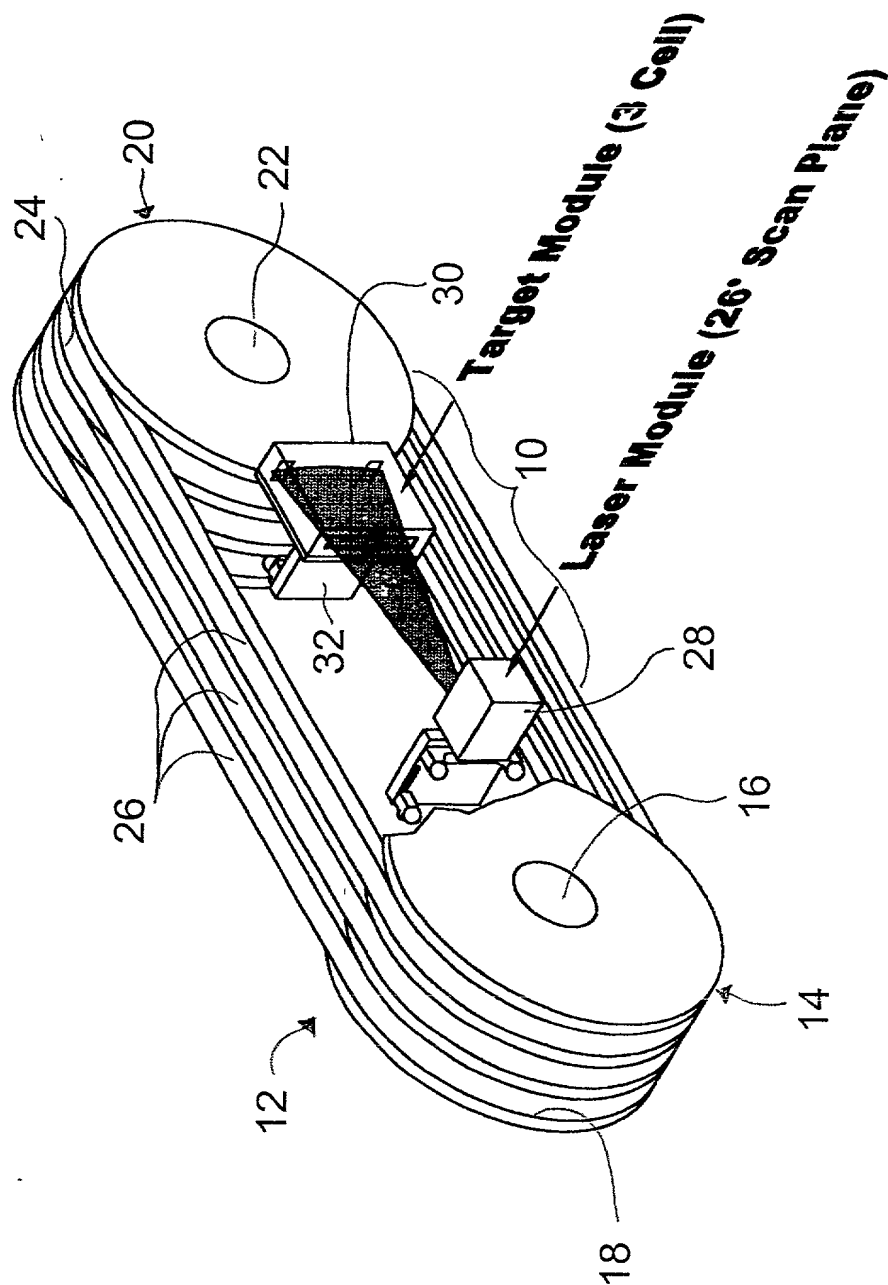


FIG. 1A

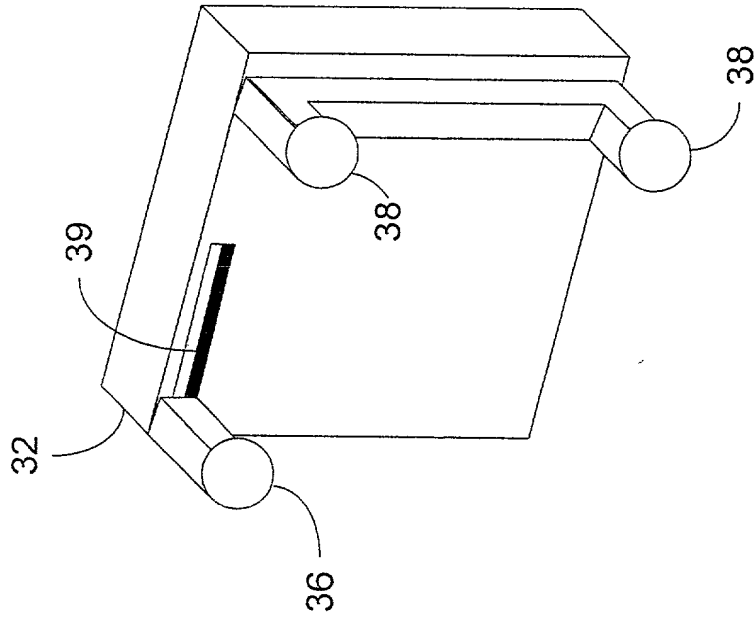


FIG. 1B

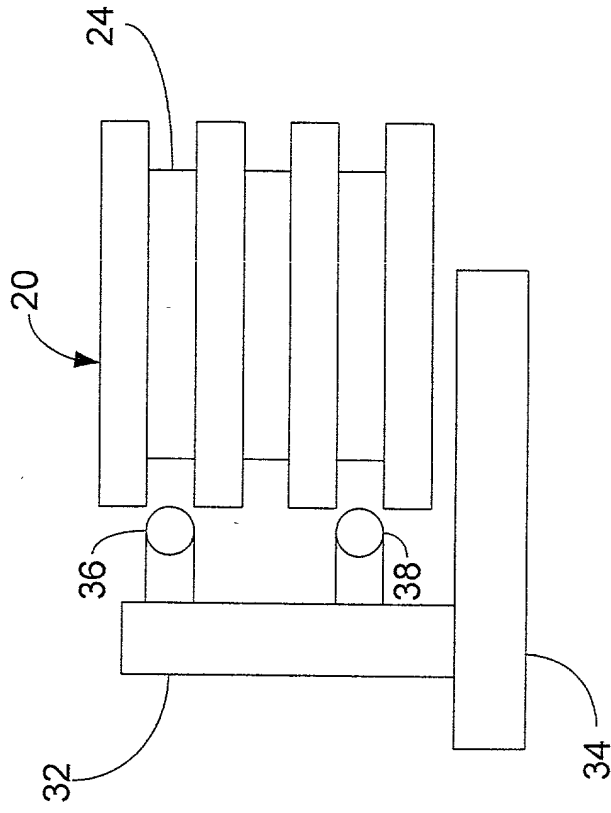


FIG. 1C

$$\begin{aligned} \text{Roll} &= B - C \\ \text{Pitch} &= A - (B + C) / 2 \\ \text{Elevation} &= (A + B + C) / 3 \end{aligned}$$

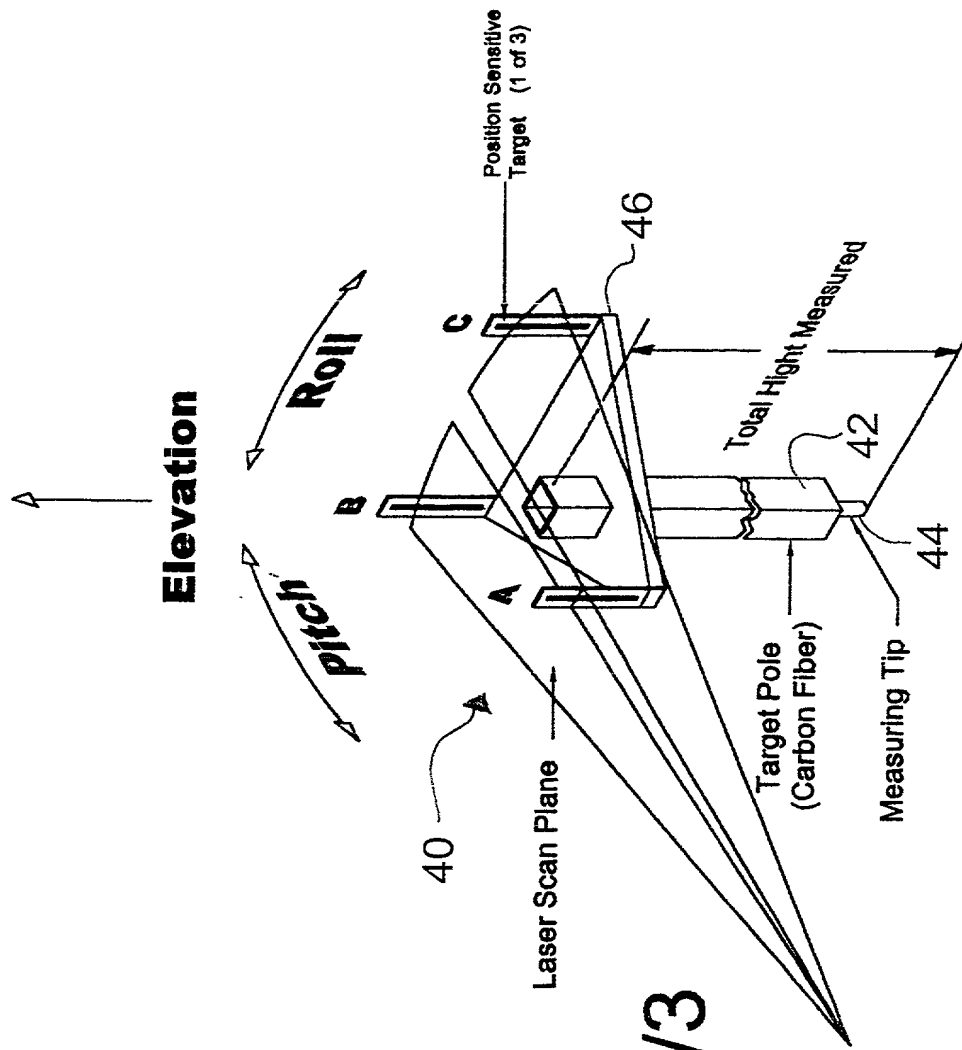


FIG. 3

DECLARATION FOR PATENT APPLICATION

Docket No. Hamar-119

As a below named inventor, I hereby declare that:

My residence, post office address and citizenship are as stated below next to my name.

I believe I am the original, first and sole inventor of the subject matter which is claimed and for which a patent is sought on the invention entitled LASER TARGET ASSEMBLY FOR SHEAVES AND HEIGHT GAGES, the specification of which is attached hereto unless the following box is checked:

☐ was filed on _____ as United States Application Number or PCT International Application Number _____ and was amended on _____ (if applicable).

I hereby state that I have reviewed and understand the contents of the above identified specification, including the claims, as amended by any amendment referred to above.

I acknowledge the duty to disclose information which is material to patentability as defined in 37 CFR § 1.56.

I hereby claim foreign priority benefits under 35 U.S.C. § 119(a)-(d) or § 365(b) of any foreign application(s) for patent or inventor's certificate, or § 365(a) of any PCT International application which designated at least one country other than the United States, listed below and have also identified below, by checking the box, any foreign application for patent or inventor's certificate, or PCT International application having a filing date before that of the application on which priority is claimed.

NONE

I hereby claim the benefit under 35 U.S.C. § 119(e) of any United States provisional application(s) listed below.

60/188,413 March 10, 2000
(Application Number) (Filing Date)

I hereby claim the benefit under 35 U.S.C. § 120 of any United States application(s), or § 365(c) of any PCT International application designating the United States, listed below and, insofar as the subject matter of each of the claims of this application is not disclosed in the prior United States or PCT International application in the manner provided by the first paragraph of 35, U. S. C. § 112, I acknowledge the duty to disclose information which is material to patentability as defined in 37 CFR § 1.56 which became available between the filing date of the prior application and the national or PCT international filing date of this application.

NONE

I hereby appoint the following attorneys to prosecute this application and to transact all business in the Patent and Trademark Office connected therewith:

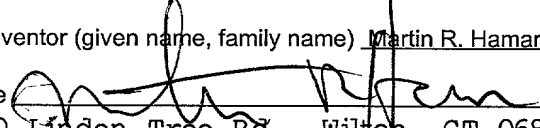
Anthony J. Casella, Atty. Reg. No. 24,095, Gerald E. Hespos, Atty. Reg. No. 30,066 and Michael J. Porco, Atty. Reg. No. 46,007
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Address all correspondence to Gerald E. Hespos
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274 Madison Avenue - Suite 1703
New York, NY 10016

I hereby declare that all statements made herein of my own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under Section 1001 of Title 18 of the United States Code and that such willful false statements may jeopardize the validity of the application or any patent issued thereon.

Full name of first inventor (given name, family name) Martin R. Hamar

Inventor's signature 
Residence 70 Linden Tree Rd., Wilton, CT 06897
Post Office Address Same

Date 7/29/00
Citizenship U.S.A.